TABLE OF CONTENTS

ADS			
ACKNOWLEDGEMENT			
TABLE OF CONTENTS			
		URESBLES	
NOT	ATIONS	SLES	VIII IX
		ION	
1.1		ING PUBLIC KEY CRYPTOSYSTEM	
1.2	PROJEC	CT MOTIVATION	2
1.3	PROJEC	CT OBJECTIVES	2
1.4	PROJEC	CT SCOPE	3
1.5		TED OUTCOME	
1.6	PROJEC	CT SCHEDULING	5
CIL	PEED 1		_
		E REVIEW	
2.1		ICRYPTION ALGORITHM	
	2.1.1	Choice of p and q	
	2.1.2	Choice of e and d	
	2.1.3	Advantages	
	2.1.4	Disadvantages	
2.2		MENTAL THEOREM OF ARITHMETIC	
2.3	FACTO	RING ALGORITHM	
	2.3.1	Trial Division	12
	2.3.2	Pollard - $ ho$ algorithm	13
	2.3.3	Quadratic Sieve Algorithm	14
		3.1 Fermat's difference-of-square Technique	
		3.2 Enhancement of difference-of-square Technique	
	2.3.	3.3 Smooth Number and Complexity	17
		3.4 The Quadratic Sieve	18
		3.5 Solving Congruence	19
		3.6 Building Factor Base	
		3.8 Choosing Appropriate Congruence	
	2.3.	3.9 Variants of Quadratic Sieve	24
2.4	DISTRI	BUTED AND PARALLEL COMPUTING	24
	2.4.1 Be	enefits of Distributed Computing	25
	2.4.2	Challenges	26
	2.4.3	Tuple Space	27
	2.4.4	JavaSpaces	
		4.1 JavaSpaces Operations	31
	2.4.	4.2 Associative Lookup	31
		4.3 Atomic Transaction	32
	2.4.5	Space-based Communication and Parallel Computing	
	2.4.6 JI	NI (Java Intelligent Network Infrastructure)	

2.5		ENCES BETWEEN LINDA AND JAVASPACES	
2.6		NT RESEARCH	
2.7	CHAPTI	ER SUMMARY	38
СНА	PTER 3		40
REQ	UIREME	NT ANALYSIS AND SYSTEM SPECIFICATION	40
3.1		A PRE-REQUISITION	
3.2		INCTIONAL REQUIREMENTS	
3.3	USE CA	SS DRIVEN ANALYSIS	
	3.3.3	Use Case Diagram	42
	3.3.2	Use Case: Start Factoring Process	44
	3.3.3	Use Case: Access Task Pool and Access Result Pool	47
	3.3.4	Use Case: Remote Access Control	49
3.4	CHAPT	ER SUMMARY	49
СНА	PTER 4.		50
SYS	TEM DES	ign	50
4.1		IA FOR PARALLEL IMPLEMENTATION	
4.2		BASED PARALLEL APPLICATION PATTERNS	
4.3		N FACTORIZATION ALGORITHM	
4.4	QS-SPA	CE ARCHITECTURE	
	4.4.1	System Operational Analysis	
	4.4.2	Data Type	
	4.4.3	Classes Identification and Design	
4.5	USER I	NTERFACE DESIGN	
	4.5.1	GUI for Master Module	
	4.5.2	GUI for Slave Module	
4.6		ASE DESIGN	
4.7		ER SUMMARY	
CHA	PTER 5.		78
	TEM IMI	PLEMENTATION AND DEPLOYMENT	78
5.1		OPMENT ENVIRONMENT ORM INDEPENDENT PROGRAMMING LANGUAGE	
5.2			
5.3		RATING JINI INTO QS-SPACE DESIGN	
	5.3.1	JINI enabled system	
	5.3.2	JavaSpaces	
5.4		DIAGRAM REFINEMENT	
5.5	QS-SPA	CE IMPLEMENTATION	
	5.5.1	Accessing JavaSpaces	
	5.5.2	Quadratic Sieve (QS) Algorithm Implementation	
	5.5.3	Integrating Sieving Stage into QSTask	
	5.5.	3.1 Sieving Algorithm	98
	5.5.4	3.2 Consideration	104
	5.5. 5.5.	4.1 Tasks Generating and Results Collecting	.105

			Slaves Coordination	
		.4.4	SieveQueue Entries Collector	
		.4.5	Execution/Running Time Analysis	
			Remote Access Service	
			Mathematic Utilities	
	5.5.5	Sla	ve Module	126
	5.5	5.1	CommandListener class	126
			Task Retrieval and Execution	
5.6	QS-SP/	\CE	DEPLOYMENT	129
	5.6.1	JIN	II's Services Deployment	129
	5.6.2	Ma	ster and Slave Module Deployment	131
	5.6.3	HT	TP Servers	132
	5.6.4	Ha	rdware and Software	133
5.7			SUMMARY	
			AL RESULT	
6.1	PERFO		NCE EVALUATION	
	6.1.1	Par	allel Benchmark	139
	6.1.2	Exe	ecution Time Proportion	142
	6.1.3	Eff	ect of Factor Base Size towards Running Time	150
6.2			NCE ANALYSIS	
6.3	OPTIMI	ZAT	TON	155
6.4			SUMMARY	
CON			ND FUTURE WORK	
7.1	CONCL	LUSI	ON	156
7.2	SUGGE	ESTI	ON FOR FUTURE WORKS	157
REF	ERENCE	S		159

LIST OF FIGURES

FIGURE 1.1 PROJECT SCHEDULE	5
FIGURE 1.1 PROJECT SCHEDULE	5
FIGURE 2.1 POLLARD- ρ	14
FIGURE 2.2 LINDA OPERATION ENVIRONMENTS	29
FIGURE 2.3 AN OVERVIEW OF JAVASPACES OPERATIONS; WRITE, TAKE AND READ	31
FIGURE 2.4 INTERACTION BETWEEN JINI'S CLIENT AND SERVICE	36
FIGURE 2.5 JINI'S DISCOVERY, JOIN AND LOOKUP	
FIGURE 3.1 USE CASE DIAGRAM FOR QS-SPACE APPLICATION	43
FIGURE 3.2 SEQUENCE DIAGRAM START FACTORING PROCESS USE CASE	45
FIGURE 3.3 ACTIVITY DIAGRAM FOR START FACTORING PROCESS::SINGLE OPERATION AND STA	RT
FACTORING PROCESS:: CONSECUTIVE OPERATION	46
FIGURE 3.4 ACTIVITY DIAGRAM FOR RESUME PREVIOUS INCOMPLETE PROCESS USE CASE	47
FIGURE 3.5 ACCESS TASK POOL USE CASES	48
FIGURE 3.6 ACCESS RESULT POOL USE CASES	48
FIGURE 3.7 REMOTE ACCESS CONTROL USE CASES	
FIGURE 4.1 REPLICATED-WORKER PATTERN	
FIGURE 4.2 COMMAND PATTERN	53
FIGURE 4.3 2-TIER ARCHITECTURE OF OS-SPACE	
FIGURE 4.4 PEER-TO-PEER DESIGN	
FIGURE 4.5 MASTER/SLAVE APPROACH WITH DYNAMIC CODES DISTRIBUTION	56
FIGURE 4.6 QS-SPACE MAIN COMPONENTS REPRESENTED IN CLASS DIAGRAM	
FIGURE 4.7 SEQUENCE DIAGRAM FOR OVERALL SYSTEM PROCESS	59
FIGURE 4.8 CLASS DIAGRAM OF QS-SPACE	61
FIGURE 4.9 MASTER MODULE GUI CLASS DIAGRAM	66
FIGURE 4.10 GUI FOR OSMASTER CONTROL PANEL	
FIGURE 4.11 DATABASE CONNECTIVITY SETUP (CLASS: DBCONNDIALOG)	69
FIGURE 4.12 INPUT BOX TO GENERATE A NEW COMPOSITE NUMBER	69
FIGURE 4.13 QS-SPACE SYSTEM CONFIGURATIONS (CLASS: SYSCONFDIALOG)	69
FIGURE 4.14 CONFIRMATION BOX FOR CONSECUTIVE BATCH	70
FIGURE 4.15 INPUT FORM FOR CONSECUTIVE BATCH COMPOSITE NUMBERS (CLASS: CONBATCHDIAL	.0G)
TIONE 4.15 IN OTTOM TOR CONDUCT TERMINET COME OF ENGINEER (CERESTORIES	
FIGURE 4.16 MESSAGE BOX FOR ACCESSIBLE SLAVE NODES IN NETWORK	
	71
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER)	71
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS: GRAFTDISPLAYER)FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS: PARALLELISM CHART)	71 72
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER)	71 72 73
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER)	71 72 73
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER)	71 72 73 74
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER)	71 72 73 74 80
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART). FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET. FIGURE 4.20 SLAVE ACTIVITIES CONSOLE. FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED FORM.	71 72 73 74 80 D IN 81
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART)	71 72 74 80 D IN 81
FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED FORM FIGURE 5.3 RETINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.3 RETINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.3 RETINED VERSION OF QS-SPACE CLASS DIAGRAM FOR THE STATE OF	71 72 74 80 D IN 81 83
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS:GRAFTDISPLAYER)	71 72 74 80 D IN 81 83 93
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS/GRAFTDISPLAYER). FIGURE 4.19 RANALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS TIROUGH JAVA APPLET FIGURE 4.10 SLAVE ACTIVITIES CONSOLE. FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTERS ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.2 REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.3 REPINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.4 GIAL SEQUENCE DIAGRAM FOR DISCOVERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM OF QS ALGORITHM PROCESS FIGURE 5.5 ACTIVITY DIAGRAM FOR DISCOVERY AND LOCKUP PROCESSES.	71 72 74 80 D IN 81 93 93
FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE TO SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE FIGURE 5.3 REFINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.4 UML SEQUENCE DIAGRAM FOR DISCOVERY AND LOOKUP PROCESSES. FIGURE 5.5 SIEVING PATTERN FOR EACH TASK ENTRY. FIGURE 5.5 SIEVING PATTERN FOR PACH TASK ENTRY.	71 72 74 80 D IN 81 83 93 97
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS/GRAFTDISPLAYER). FIGURE 4.19 RANALLELISM CHART FOR SIENING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET. FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTERS ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.2 REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.3 REPINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.3 REPINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.5 ACTIVITY DIAGRAM OF QS ALGORITHM PROCESS. FIGURE 5.5 ACTIVITY DIAGRAM FOR SHOOTS ACTIVITY PROCESS. FIGURE 5.7 ACTIVITY DIAGRAM FOR NODESCOORDINATOR. FIGURE 5.7 ACTIVITY DIAGRAM FOR NODESCOORDINATOR.	71727480 D IN8183979791
FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED FORM FIGURE 5.3 REFINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.4 LIMIL SEQUENCE DIAGRAM FOR DISCOVERY AND LOOKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM OF QS ALGORITHM PROCESS FIGURE 5.5 SIEVING PATTERN FOR EACH TASK ENTRY. FIGURE 5.5 ACTIVITY DIAGRAM FOR NON DOSSCOORDINATOR: FIGURE 5.8 ACTIVITY DIAGRAM FOR NODESCOORDINATOR: FIGURE 5.8 ACTIVITY DIAGRAM FOR NODESCOORDINATOR: FIGURE 5.5 ACTIVITY DIAGRAM FOR NODESCOORDINATOR: FIGURE 5.9 ACTIVITY DIAGRAM FOR NODESCOORDINATOR: FIGURE	71727480 D IN8183939791111
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS/GRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART FOR SIENING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.19 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS FIGURE 5.2 ALL ENTRIES ARE SERVALEED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.3 RESINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.3 RESINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.5 ACTIVITY DIAGRAM FOR SIDONEYRY AND LOCKUP PROCESSES FIGURE 5.5 ACTIVITY DIAGRAM FOR NODES/COORDINATOR FIGURE 5.7 ACTIVITY DIAGRAM FOR NODES/COORDINATOR FIGURE 5.5 ACTIVITY DIAGRAM FOR NODES/COORDINATOR FIGURE 5.9 ACTIVITY DIAGRAM FOR NODES/COORDINATOR FIGURE 5.10 ACTIVITY DIAGRAM FOR NODES/COORDINATOR FIGURE	71727480 D IN8183979791111113
FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED FORM FIGURE 5.3 RETINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.3 RETINED VERSION OF QS-SPACE CLASS DIAGRAM FIGURE 5.5 ACTIVITY DIAGRAM FOR SOLOWERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR BODISCOORDINATOR. FIGURE 5.5 ACTIVITY DIAGRAM FOR NODESCOORDINATOR. FIGURE 5.10 ACTIVITY DIAGRAM FOR NODESCOORDINATOR.	71727480 D IN81939791113114115
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASSGRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART POR SIENING PROCESS (CLASS-PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH LAVA APPLET. FIGURE 5.10 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTRIES ARE SERVALEED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE THE SERVICE SERVICE PROXY OBJECT AND TRANSMITTED AND STOKE THE SERVICE SERVICE PROXY OBJECT AND TRANSMITTED AND STOKE THE SERVICE SERVICE SERVICE PROXY OBJECT AND TRANSMITTED AND STOKE THE SERVICE S	7172737480 D IN819397111113114115118122
FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE AND TRANSMITTED AND TRANSMITTED AND STORE THE REMOTE SPACE AND TRANSMITTED AND TRANSMITTED AND TRANSMITTED AND TRANSMITTED AND TRANSMITTED AND TORE THE REMOTE SPACE AND TRANSMITTED AND TRANSMI	71727480 DIN81939799111113114115118122
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASSGRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART FOR REIVING PROCESS (CLASS-PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH LAVA APPLET. FIGURE 5.19 REMOTE ACCESS THROUGH LAVA APPLET. FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS	7172737480 DIN81839799111113114115118122127
FIGURE 4.18 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 PARALLELISM CHART FOR SIEVING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 PARMOTE ACCESS TIRROUGH JAVA APPLET FIGURE 4.20 SLAVE ACTIVITIES CONSOLE FIGURE 5.2 ALL ENTERES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE THE REMOTE SPACE IN SERIALIZED FORM. FIGURE 5.2 ALL ENTERES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.3 REFINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.3 REFINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.5 ACTIVITY DIAGRAM FOR SOCIETY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR SOCIETY AND LOCKUP PROCESSES. FIGURE 5.7 ACTIVITY DIAGRAM FOR NODESCOORDINATOR. FIGURE 5.7 ACTIVITY DIAGRAM FOR NODESCOORDINATOR. FIGURE 5.10 ACTIVITY DIAGRAM FOR NODESCOORDINATOR. FIGURE 5.10 ACTIVITY DIAGRAM FOR NODESCOORDINATOR: PATROLLY FIGURE 5.11 CONSTRUCTIVE DIAGRAM FOR NODESCOORDINATOR: PATROLLY FIGURE 5.12 REMOTE ACCESS VIA RMI. FIGURE 5.12 REMOTE ACCESS VIA RMI. FIGURE 5.14 PACKAGES AND THEIR RELATIONSHIP. FIGURE 5.14 PACKAGES AND THEIR RELATIONSHIP.	7172737480 DIN819397111113114115118122127129
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASSGRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART FOR REIVING PROCESS (CLASS-PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED FORM. FIGURE 5.3 RETINED YERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.3 CALTIVITY DIAGRAM FOR SOCIOVERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PROCESSES. FIGURE 5.7 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PROCESSES. FIGURE 5.9 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PROCESSES. FIGURE 5.5 DACTIVITY DIAGRAM FOR MODISCOORDINATOR: PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PROFILED FOR THE MADERIAL PROPERTY OF THE PR	7172737480 DIN819397111113114115118122127129130
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS/GRAFTDISPLAYER). FIGURE 4.19 REMAILE LISM CHART FOR SIENING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS TIRROUGH JAVA APPLET. FIGURE 5.1 PARALLELISM CHART FOR SIENING PROCESS (CLASS:PARALLELISMCHART) FIGURE 5.1 PASSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.3 RESINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.3 RESINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.5 ACTIVITY DIAGRAM FOR SIENIALIZED DOVERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR SOCIOBRATOR. FIGURE 5.5 ACTIVITY DIAGRAM FOR SOCIOBRATOR. FIGURE 5.7 ACTIVITY DIAGRAM FOR MODISCOORDINATOR. FIGURE 5.9 ACTIVITY DIAGRAM FOR NODISCOORDINATOR. FIGURE 5.9 ACTIVITY DIAGRAM FOR NODISCOORDINATOR. FIGURE 5.10 ACTIVITY DIAGRAM FOR NODISCOORDINATOR: PATROLL) FIGURE 5.10 ACTIVITY DIAGRAM FOR NODISCOORDINATOR: PATROLL) FIGURE 5.11 POSSIBLE ARRANGEMENT OF SIEVE TIME FIGURE 5.12 REMOTE ACCESS VIA RMI. FIGURE 5.14 PACKAGES AND THEIR RELATIONSHIP. FIGURE 5.16 DEPLOYMENT TIME.	7172737480 D IN819397111113114115122127129130135140
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASSGRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART FOR RIENING PROCESS (CLASS-PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED FORM. FIGURE 5.3 RETINED YERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.3 CALL BEQUINED ENDROGRAM FOR DISCOVERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR SOLOWERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.7 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.5 DACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.5 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.10 TOTAL THE ARRANGEMENT OF SIEVE TIME FIGURE 5.11 POSSIBLE ARRANGEMENT OF SIEVE TIME FIGURE 5.13 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PATROL(). FIGURE 5.13 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PATROL(). FIGURE 5.15 INTERACTION IN QS-SPACE. FIGURE 5.15 INTERACTION IN QS-SPACE. FIGURE 6.1 TOTAL EXECUTION TIME.	7172737480 D IN819397111113114115122127130130130
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASS/GRAFTDISPLAYER). FIGURE 4.19 RANALLELISM CHART FOR SIENING PROCESS (CLASS:PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS TIROUGH JAVA APPLET. FIGURE 4.10 SLAVE ACTIVITIES CONSOLE. FIGURE 5.2 CALL ENTERES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.2 REMOTE SPACE IN SERIALIZED DEVI LOCAL PROXY OBJECT AND TRANSMITTED AND STOKE FIGURE 5.3 REFINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.3 REFINED VERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.5 ACTIVITY DIAGRAM FOR SICHOLYBRY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR SOCIED STRIPLY. FIGURE 5.7 ACTIVITY DIAGRAM FOR MODISCOORDINATOR. FIGURE 5.7 ACTIVITY DIAGRAM FOR NODISCOORDINATOR. FIGURE 5.9 ACTIVITY DIAGRAM FOR NODISCOORDINATOR. FIGURE 5.9 ACTIVITY DIAGRAM FOR NODISCOORDINATOR. FIGURE 5.10 ACTIVITY DIAGRAM FOR NODISCOORDINATOR. FIGURE 5.10 ACTIVITY DIAGRAM FOR NODISCOORDINATOR. FIGURE 5.11 POSSIBLE ARRANGEMENT OF SIEVE TIME FIGURE 5.12 REMOTE ACCESS VIA RMI FIGURE 5.14 PACKAGES AND THEIR RELATIONSHIP. FIGURE 5.16 DEPLOYMENT DIAGRAM FOR GOS-SPACE. FIGURE 5.16 DEPLOYMENT DIAGRAM FOR GOS-SPACE. FIGURE 6.16 DEPLOYMENT DIAGRAM FOR SEPACE. FIGURE 6.2 TOTAL SPECIAL TIME COMPOSITION FOR SEPACE. FIGURE 6.2 TOTAL SEPCIDITY DIAGRAM FOR GOS-SPACE. FIGURE 6.2 TOTAL SEPCIDITY DIAGRAM FOR GOS-SPACE.	7172737480 DIN819397111113114115122127129130131
FIGURE 4.17 SYSTEM PERFORMANCE GRAFT (CLASSGRAFTDISPLAYER). FIGURE 4.18 PARALLELISM CHART FOR RIENING PROCESS (CLASS-PARALLELISMCHART) FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 4.19 REMOTE ACCESS THROUGH JAVA APPLET FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.1 POSSIBLE ARRANGEMENT OF JINI-ENABLED COMPONENTS. FIGURE 5.2 ALL ENTRIES ARE SERIALIZED BY LOCAL PROXY OBJECT AND TRANSMITTED AND STORE THE REMOTE SPACE IN SERIALIZED FORM. FIGURE 5.3 RETINED YERSION OF QS-SPACE CLASS DIAGRAM. FIGURE 5.3 CALL BEQUINED ENDROGRAM FOR DISCOVERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR SOLOWERY AND LOCKUP PROCESSES. FIGURE 5.5 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.7 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.5 DACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.5 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: INSCOVERNODES(). FIGURE 5.10 TOTAL THE ARRANGEMENT OF SIEVE TIME FIGURE 5.11 POSSIBLE ARRANGEMENT OF SIEVE TIME FIGURE 5.13 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PATROL(). FIGURE 5.13 ACTIVITY DIAGRAM FOR MODISCOORDINATOR: PATROL(). FIGURE 5.15 INTERACTION IN QS-SPACE. FIGURE 5.15 INTERACTION IN QS-SPACE. FIGURE 6.1 TOTAL EXECUTION TIME.	7172737480 DIN81939799111113114115122127129130135144

FIGURE 6.6 RUN TIME COMPOSITION FOR PARALLEL IMPLEMENTATION [SLAVE NODES=3]	
FIGURE 6.7 RUN TIME COMPOSITION FOR PARALLEL IMPLEMENTATION [SLAVE NODES=4]	.147
FIGURE 6.8 RUN TIME COMPOSITION FOR PARALLEL IMPLEMENTATION [SLAVE NODES=5]	. 148
FIGURE 6.9 RUN TIME COMPOSITION FOR PARALLEL IMPLEMENTATION [SLAVE NODES=6]	
FIGURE 6.10 RELATIONSHIP BETWEEN FACTOR BASE AND QS EXECUTION TIME	.150
FIGURE 6.11 TOTAL EXECUTION TIME WITH DIFFERENT FACTOR BASE SIZE (DIGIT LENGTH=45)	.151
FIGURE 6.12 TOTAL EXECUTION TIME WITH DIFFERENT FACTOR BASE SIZE (DIGIT LENGTH=50)	.151
FIGURE 6.13 TOTAL EXECUTION TIME WITH DIFFERENT FACTOR BASE SIZE (DIGIT LENGTH=55)	152

List of Tables

	PRIME FACTORS FOR POSITIVE INTEGER	
	C VALUE	
TABLE 2.3	FACTORING RECORD SINCE 1970 [MON1995]	24
TABLE 4.1	BATCH TABLE	75
TABLE 4.2	SIEVETIME TABLE	76
TABLE 4.3	B SMOOTH RETURNED TABLE	76
TABLE 4.4	SLAVEINFO TABLE	76
TABLE 6.1	NUMBER TO BE FACTORIZED IN EACH TEST RUNS	138
TABLE 6.2	PARAMETER VALUES ASSIGNED TO EACH TEST NUMBER	139
	TOTAL EXECUTION TIME FOR EACH FACTORING EXERCISE WITH INCREASING NUMBER OF	
TABLE OIL	SLAVE NODES	139
	SPEEDUP RELATIVE TO SERIAL IMPLEMENTATION	
TABLE 6.5	EXECUTION TIME FOR SERIAL IMPLEMENTATION	143
	EXECUTION TIME FOR NUMBER OF SLAVE NODES = 1	
	EXECUTION TIME FOR NUMBER OF SLAVE NODES =2	
	EXECUTION TIME FOR NUMBER OF SLAVE NODES =3	
	EXECUTION TIME FOR NUMBER OF SLAVE NODES =4	
	0 EXECUTION TIME FOR NUMBER OF SLAVE NODES =5	
TABLE 6.1	1 EXECUTION TIME FOR NUMBER OF SLAVE NODES =6	149
	2 COMMUNICATION/COMPUTATION RATIO IN 6 SLAVE NODES	
	3 ENTRY SIZE	
	4 SPEEDUP OPTIMIZATION ON SIEVE TIME [NODES=6]	

Notations

Symbol	Meaning
$a \equiv b \pmod{n}$	a is congruent to b modulus n
a b	a divides b
a√ b	a does not divide b
$\varphi(n)$	Euler's totient function
G.C.D(a,b)	greatest common divisor of a and b
[a, b]	the interval $a \le x \le b$
П	product symbol where $\prod_{i=1}^{n} a_{i} \cdot a_{2} \cdot \dots \cdot a_{n}$
p	a prime number
$\left\lceil \frac{a}{p} \right\rceil$	
$\lfloor p \rfloor$	Legendre symbol, defined if p is an odd prime
N	Modulus of RSA algorithm